## Integrated Stepper Motor User Manual


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## Notice

Read this manual carefully before any assembling and using. Incorrect handling of products in this manual can result in injury and damage to persons and machinery. Strictly adhere to the technical information regarding installation requirements.

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## - Thank you for purchasing Leadshine iEM Series Products

- Please read this manual carefully before operating
$\bullet$ Please keep this manual appropriately


## Record of Revisions

| Manual <br> Revision | Data |  |
| :---: | :---: | :---: |
| V 1.0 | $02 / 25 / 2022$ | Description of Release |
|  |  | Initial Release |

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## 1 Introduction

### 1.1 Product Introduction

iEM series is Leadshine stepper motor integrated a digital stepper drive. It implements advanced control algorithm of Leadshine based on its tens of years' experience in stepper and servo controls. At very compact size can save mounting space, eliminate motor wiring time, reduce interference, and cut/reduce cable and labor costs.

The iEM series are reliable and affordable and performs excellent in many industrial applications such as CNC, 3D printer, stage equipment, medical, electronics, packaging...

### 1.2 Features

- No tuning for easy setup
- Soft-start with no "jump" when powered on
- Low noise and vibration, smooth motion
- Step\&Direction and CW\&CCW control
- 3 digital inputs, 1 optically isolated digital output
- RS232 communication for Leadshine software connection
- Over voltage, over current protections


### 1.3 Applications

The iEM series can be adopted in many low to median speed applications such as 3 D printer, lab automation instruments, plotters, medical equipment, electronic equipment, small packaging machines, etc.

## 2. Specifications

### 2.1 Electrical Specifications

| Model | Frame Size | $\begin{aligned} & \text { Length } \\ & (\mathrm{mm}) \end{aligned}$ | Holding Torque (N.m) | $\begin{aligned} & \text { Weight } \\ & \text { (Kg) } \end{aligned}$ | Command Source |  | Electrical Parameters |  | Control Signal |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | PUL\& DIR | CW\& CCW | Power Voltage (VDC) | Peak Current (A) | Logical Current | Logical <br> Voltage | Max Input Frequency | MIN PUL Width | MIN DIR Setup |
| iEM-1703 |  | 64 | 0.3 | 0.5 | $\checkmark$ | x | 20-36 | 0.3-3.0 | 7-16mA | 5 V | 200 KHz | $2.5 \mu \mathrm{~s}$ | 5.0 $\mu \mathrm{s}$ |
| iEM-1706 | $\begin{gathered} \text { NEMA } \\ 17 \end{gathered}$ | 72 | 0.6 | 0.9 | $\checkmark$ | x | 20-36 | 0.3-3.0 |  |  |  |  |  |
| iEM-1708 |  | 85 | 0.8 | 1.1 | $\checkmark$ | x | 20-36 | 0.3-3.0 |  |  |  |  |  |
| iEM-2313 | $\begin{gathered} \text { NEMA } \\ 23 \end{gathered}$ | 75 | 1.3 | 1.0 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-4.5 |  |  |  |  |  |
| iEM-2323 |  | 96 | 2.3 | 1.3 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-7.0 |  |  |  |  |  |
| iEM-2321-L |  | 89 | 2.1 | 1.4 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-7.0 |  |  |  |  |  |
| iEM-2331-L |  | 109 | 3.1 | 1.6 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-7.0 |  |  |  |  |  |
| iEM-2430 | $\begin{gathered} \text { NEMA } \\ 24 \end{gathered}$ | 109 | 3.0 | 1.6 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-7.0 |  |  |  |  |  |
| iEM-2435 |  | 122 | 3.5 | 1.9 | $\checkmark$ | $\checkmark$ | 20-50 | 0.5-7.0 |  |  |  |  |  |

### 2.2 Environment

| Cooling |  | Natural Cooling or Forced Cooling |  |
| :---: | :---: | :---: | :---: |
|  | Environment | Avoid dust, oil fog and corrosive gases |  |
| Operating Environment | Humidity | $40 \% \mathrm{RH}-90 \% \mathrm{RH}$ |  |
|  | Operating Temperature | $0^{\circ} \mathrm{C}-40^{\circ} \mathrm{C}\left(32^{\circ} \mathrm{F}-104^{\circ} \mathrm{F}\right)$ |  |
| Storage Temperature | Vibration | $10-50 \mathrm{~Hz} / 0.15 \mathrm{~mm}$ |  |

### 2.3 Dimensions

> (unit: mm [1inch=25.4mm])

.2


| Models | L1 length | L length |
| :---: | :---: | :---: |
| iEM-1703 | 43 | 64 |
| iEM-1706 | 51 | 72 |
| iEM-1708 | 64 | 85 |



| Models | L1 length | L length |
| :---: | :---: | :---: |
| iEM-2313 | 54 | 75 |
| iEM-2323 | 75 | 96 |
| iEM-2321-L | 68 | 89 |
| iEM-2331-L | 88 | 109 |
| iEM-2430 | 88 | 109 |
| iEM-2435 | 101 | 122 |




Note: (1) Frame size is 60 mm , center diameter is 36 mm .
(2) Frame size is 60 mm , center diameter is 36 mm , shaft diameter is 10 mm
Figure 1: Mechanical specifications

## 3. Connections and LED Indication



Figure 2: iEM series motor connectors

### 3.1 Connector P1 - Power \& Control \& Digital Outputs Connector

### 3.1.1 Pin Assignments of P 1

The P1 connector in Figure 2 contains connections for control signals and 2 digital output.
See the following table for details.

| PIN | I/O | Details |
| :---: | :---: | :---: |
| VCC | I | Power supply positive connection. 20-36VDC power supply voltage |
| GND | I | Power supply ground connection. |
| ALM- | 0 | Alarm: An OC output signal. It takes a sinking or sourcing at 5-24V@30mA |
| ALM + | O |  |
| ENA- | I | Enable Signals: Optional, not connected by default. <br> (1) Effective high level is $4.5-5 \mathrm{~V}$; Effective low level is $0-0.5 \mathrm{~V}$ connection <br> (2) ENA signal requires advance DIR signal minimum 200 ms in single pulse mode |
| ENA+ | I |  |
| DIR- | I | Pulse and Direction Connection: <br> (1) Optically isolated, high level $4.5-5 \mathrm{~V}$, low voltage $0-0.5 \mathrm{~V}$. <br> (2) Max 200 KHz input frequency. <br> (3) The width of PUL signal is at least $2.5 \mu \mathrm{~s}$, duty cycle is recommended $50 \%$. <br> (4) Single pulse (step \& direction), iEM-23xx and iEM-24xx support double pulse (CW\&CCW), while iEM-17xx do not support. <br> (5) DIR signal requires advance PUL signal minimum $5 \mu \mathrm{~s}$. |
| DIR+ | I |  |
| PUL- | I |  |
| PUL+ | I |  |

Notes: (1) Shielding control signal wires is suggested; (2) To avoid/reduce interference, do not tie control signal cables and power wires together.

### 3.1.2 Connection of Control Signals

The iEM series motor can accept differential and single-ended control signal inputs (open-collector and PNP output). It has 3 optically isolated control inputs, PUL, DIR, and ENA. Refer to the following two figures for connections of PNP and NPN signals.


Figure 3: Control Signals Connection
Notes: (1) ENA signal is no connected as default;
(2) If the logic voltage is not 5 V , it needs to connect resistors.

### 3.1.3 Connection of ALM Signal

Alarm output is the default configuration. This output signals a fault condition including over-voltage, over-current, or position following error. This output can be used to drive devices such as a relay, a LED, etc., or as an input signal to electronic devices like a PLC.
For example, in a multi-axis system like a CNC machine when one of the axes fails such a fault output signal can be feedback to the motion controller for a followed action (e.g., auto machine shutdown, auto error clearing, etc.).


Figure 4: ALM Signals Connection

### 3.1.4 Connection of Power Supply

| Pin Name | Details |
| :--- | :--- |
|  | Power supply positive connection. |
| +VDC | iEM-17xx:20-36VDC |
|  | iEM-23xx and iEM-24xx: 20-50 VDC |
| GND | Power supply ground connection. |

Notes: It is recommended that power voltage of all integrated motors are 24 VDC , otherwise if the motor is too hot, it is easy to transfer heat to the drive, thus damaging the drive.

### 3.2 Connector P2 - Tuning Port

The P2 connector in Figure 2 is a RS232 communication port for Leadshine software connection. It is just used to modify parameter, not for equipment control because neither precision nor stability is sufficient. If you need a Modbus-RS485 control, use a Leadshine iEM-RS series integrated stepper motor.The interface definition is as follows:


Female DB9
(Look from the front side)
Figure5: RS232 Tuning Port

### 3.3 LED Light Indication

There are two LED lights for iEM motor, one is red and another is green. The GREEN one is the power indicator which will be always on generally. The RED one is a protection indicator. It is off always when a iEM motor operates normally, but will flash 1 , 2 or 7 times in a 5 -second period when error protection is enabled. Different number of flashes indicates different protection type.


| 1 |  | Over-current | Turn off the power immediately. <br> a) Check wiring is short-circuited or not; <br> b) Check motor is short-circuited or not. |
| :---: | :---: | :---: | :---: |
| 2 |  | Over-voltage | Turn off the power immediately. <br> a) Check if the power voltage is higher than 90VDC |
| Always | - | PCB board is burned out | Contact after-sale <br> a) Power supply connection is wrong |

When above protections are active, the motor shaft will be free and the red LED blinks. Reset the drive by repowering it to make it function properly after removing above problems.

## 4. DIP Switch Configurations

The iEM series has a row of DIP switches, of which the iEM17xx and iEM-23xx DIP switches are a bit different, as follows,


### 4.1 Microstep Resolution (SW1-SW4)

- For iEM-17xx Series

Microstep resolution is set by SW1, 2, 3, 4 of the DIP switches as shown in the following table:

| Steps/Revolution | SW1 | SW2 | SW3 | SW4 |
| :---: | :---: | :---: | :---: | :---: |
| 200 (Default) | on | on | on | on |
| 400 | off | on | on | on |
| 800 | on | off | on | on |
| 1600 | off | off | on | on |
| 3200 | on | on | off | on |
| 6400 | off | on | off | on |
| 12800 | on | off | off | on |
| 25600 | off | off | off | on |
| 1000 | on | on | on | off |
| 2000 | off | on | on | off |
| 4000 | on | off | on | off |
| 5000 | off | off | on | off |
| 8000 | on | on | off | off |
| 10000 | off | on | off | off |
| 20000 | on | off | off | off |
| 25000 | off | off | off | off |

- For iEM-23xx and iEM-24xx Series

| Steps/Revolution | SW1 | SW2 | SW3 | SW4 |
| :---: | :---: | :---: | :---: | :---: |
| $\mathbf{4 0 0}$ (Default) | on | on | on | on |
| $\mathbf{8 0 0}$ | off | on | on | on |
| $\mathbf{1 6 0 0}$ | on | off | on | on |
| $\mathbf{3 2 0 0}$ | off | off | on | on |
| $\mathbf{6 4 0 0}$ | on | on | off | on |
| $\mathbf{1 2 8 0 0}$ | off | on | off | on |
| $\mathbf{2 5 6 0 0}$ | on | off | off | on |
| $\mathbf{5 1 2 0 0}$ | off | off | off | on |
| $\mathbf{1 0 0 0}$ | on | on | on | off |
| $\mathbf{2 0 0 0}$ | off | on | on | off |
| $\mathbf{4 0 0 0}$ | on | off | on | off |

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| $\mathbf{5 0 0 0}$ | off | off | on | off |
| :---: | :---: | :---: | :---: | :---: |
| $\mathbf{8 0 0 0}$ | on | on | off | off |
| $\mathbf{1 0 0 0 0}$ | off | on | off | off |
| $\mathbf{2 0 0 0 0}$ | on | off | off | off |
| $\mathbf{4 0 0 0 0}$ | off | off | off | off |

### 4.2 Other DIP Switch Settings

- For iEM-17xx Series (SW5-SW6)

|  | Function | On | Off |
| :---: | :---: | :---: | :---: |
| SW5 | Default Direction | CW (clockwise) | CCW (counterclockwise) |
| SW6 | Reserved | - | - |

- For iEM-23xx and iEM-24xx Series (SW5-SW8)

|  | Function | On | Off |
| :---: | :---: | :---: | :---: |
| SW5 | Default Direction | CW (clockwise) | CCW (counterclockwise) |
| SW6 | Pulse Mode | CW\&CCW | PUL\&DIR |
| SW7 | Smoothing Time | Enable | Disable |
| SW8 | Activated Edge | Rising edge | Falling edge |

## 5. Accessories

If you plan to use the Leadshine software, contact your supplier or Leadshine to purchase the RS232 cable with part number CABLE-PC-1 for V2.0 version motor (CABLE-PC-ICL42 for V1.0 version motor). In the case of using USB to RS232 conversion, contact your supplier or Leadshine for such a cable with part number USB2.0-232 which has been verified working fine.


CABLE-PC-1 (RS232 tuning cable)


USB2.0-232
(USB to RS232 Conversion Cable)

## 6. Warranty

## Twelve Month Warranty

Leadshine Technology Co., Ltd. warrants its products against defects in materials and workmanship for a period of 12 months from shipment out of factory. During the warranty period, Leadshine will either, at its option, repair or replace products which proved to be defective.

## Exclusions

The above warranty does not extend to any product damaged by reasons of improper or inadequate handlings by customer, improper or inadequate customer wirings, unauthorized modification or misuse, or operation beyond the electrical specifications of the product and/or operation beyond environmental specifications for the product.
Obtaining Warranty Service
To obtain warranty service, please contact your seller to obtain a returned material authorization number (RMA) before returning product for service.

## Shipping Failed Products

If your product fail during the warranty period, please contact your seller for how and where to ship the failed product for warranty or repair services first, you can also e-mail customer service at tech@leadshine.com to obtain a returned material authorization number (RMA) before returning product for service. Please include a written description of the problem along with contact name and address.

